Package: dsmSearch (via r-universe)

June 9, 2026

Type Package

Title DSM and LiDAR Downloader

Version 1.2.2

Description A collection of functions to search and download Digital Surface Model (DSM) and Light Detection and Ranging (LiDAR) data via APIs, including 'OpenTopography' <https://portal.opentopography.org/apidocs/> and 'TNMAccess' <https://apps.nationalmap.gov/tnmaccess/#/>, and canopy tree height data.

Depends R (>= 4.1)

License GPL-3

Encoding UTF-8

RoxygenNote 7.3.2

Language en-US

Suggests testthat (>= 3.0.0), knitr, rmarkdown

VignetteBuilder knitr, rmarkdown

Imports dplyr, sf, sp, terra, lidR, httr2, nominatimlite, imager, cli, aws.s3, stringr

NeedsCompilation no

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Config/pak/sysreqs libabsl-dev cmake libfftw3-dev libfreetype6-dev libgdal-dev gdal-bin libgeos-dev libglpk-dev libglu1-mesa-dev make texlive libicu-dev libjpeg-dev libpng-dev libtiff-dev libuv1-dev libxml2-dev libgl1-mesa-dev libssl-dev libproj-dev libsqlite3-dev libudunits2-dev libx11-dev zlib1g-dev

Repository https://cranhaven.r-universe.dev

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RemoteRef package/dsmSearch

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Contents

`get_dsm_30` *get_dsm_30*

Description

Search for and download Digital Surface Model based on coordinates of a spatial point with a given distance or bounding box. The resolution of AW3D30 (ALOS World 3D 30m) and SRTMGL1 (SRTM GL1 30m) raster is 30 meter. The raster resolutions of USGS datasets are 10m and 1m. Forest canopy height maps (CHM) include the ETH Global Sentinel-2 10m Canopy Height (2020) and the Meta High Resolution 1m Global Canopy Height Map

Usage

```
get_dsm_30(x, y, r, epsg, bbox, datatype = "AW3D30", key = "")
```

Arguments

`x`	numeric, indicating Longtitude degree of the center point. (bbox is specified, this argument is ignored)
`y`	numeric, indicating latitude degree of the center point. (bbox is specified, this argument is ignored)
`r`	numeric, indicating search distance (meter or feet) for LiDAR data. (bbox is specified, this argument is ignored)
`epsg`	numeric, the EPSG code specifying the coordinate reference system. (bbox is specified, this argument is ignored)
`bbox`	vector, a bounding box defining the geographical area for downloading data.
`datatype`	character, dataset names including "AW3D30", "SRTMGL1", "USGS1m", "USGS10m", "metaCHM", and "ethCHM".
`key`	character, API key of OpenTopography. (not required for "metaCHM", and "ethCHM")

Details

To request an API key of OpenTopography, online registeration is needed.

To get CHMs with more customized arguments please use `fd_canopy_height` from the `forestdata` package.

Data may be freely used for academic purposes, but be cited appropriately (see references below).

Value

SpatRaster raster

References

Japan Aerospace Exploration Agency (2021). ALOS World 3D 30 meter DEM. V3.2, Jan 2021. Distributed by OpenTopography. https://doi.org/10.5069/G94M92HB. Accessed: 2025-06-04

United States Geological Survey (2021). United States Geological Survey 3D Elevation Program 1 meter Digital Elevation Model. Distributed by OpenTopography. https://doi.org/10.5069/G9NP22NT. Accessed: 2025-06-04

United States Geological Survey (2021). United States Geological Survey 3D Elevation Program 1/3 arc-second Digital Elevation Model. Distributed by OpenTopography. https://doi.org/10.5069/G98K778D. Accessed: 2025-06-04

United States Geological Survey (2021). United States Geological Survey 3D Elevation Program 1 arc-second Digital Elevation Model. Distributed by OpenTopography. https://doi.org/10.5069/G9HX19WN. Accessed: 2025-06-04

Lang, Nico, Walter Jetz, Konrad Schindler, and Jan Dirk Wegner. "A high-resolution canopy height model of the Earth." arXiv preprint arXiv:2204.08322 (2022).

Tolan, J., Yang, H.I., Nosarzewski, B., Couairon, G., Vo, H.V., Brandt, J., Spore, J., Majumdar, S. , Haziza, D., Vamaraju, J. and Moutakanni, T., 2024. Very high resolution canopy height maps from RGB imagery using self-supervised vision transformer and convolutional decoder trained on aerial lidar. Remote Sensing of Environment, 300, p.113888.

Examples

```
## Not run:
data <- dsmSearch::get_dsm_30(bbox = c(-83.783557,42.241833,-83.696525,42.310420),
                              key = "API key")
data <- dsmSearch::get_dsm_30(x = -83.741289,
                              y = 42.270146,
                              r = 1000,
                              epsg = 2253,
                              key = "API key")

## End(Not run)
```

get_lidar *get_lidar*

Description

Search for and download LiDAR data based on coordinates of a spatial point with a given distance or a bounding box. The maximum distance is 1000m. Different dataset could be found and the function automatically downloads the latest dataset. To get more details of data on a larger scale, please use viewscape::lidar_search.

Usage

```
get_lidar(
  x,
  y,
  r,
  epsg,
  bbox,
  max_return = 1000,
  folder = NULL,
  iftest = FALSE
)
```

Arguments

x	numeric, indicating Longtitude degree of the center point.
y	numeric, indicating latitude degree of the center point.
r	numeric, indicating search distance for LiDAR data. The maximum distance is 1000m (3281ft). If r > 1000m, it will be reset to 1000m.
epsg	numeric, the EPSG code specifying the coordinate reference system.
bbox	vector, a bounding box defining the geographical area for downloading data.
max_return	numeric, indicating the maximum of returns.
folder	string (optional), indicating a path for downloading the LiDAR data
iftest	logical, if true, run this in the test mode.

Value

lidR LAS object.

References

Jean-Romain Roussel and David Auty (2022). Airborne LiDAR Data Manipulation and Visualization for Forestry Applications. R package version 4.0.1. https://cran.r-project.org/package=lidR

See Also

lidar_search()

Examples

```
# set `test` to `FALSE` to run
las <- dsmSearch::get_lidar(x = -83.741289, y = 42.270146,
                            r = 1000, epsg = 2253, iftest = TRUE)
las <- dsmSearch::get_lidar(bbox = c(-83.742282,42.273389,
                                     -83.733442,42.278724),
                            epsg = 2253, iftest = TRUE)
```

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lidar_search *lidar_search*

Description

The lidar_search function is designed to facilitate the retrieval and exploration of LiDAR (Light Detection and Ranging) data within a specified bounding box (bbox). This function enables users to search for LiDAR data, preview available graphics, and optionally download LiDAR data files for further analysis.

Usage

```
lidar_search(bbox, max_return = 500, preview = FALSE, folder = "")
```

Arguments

bbox	vector, a bounding box defining the geographical area for the LiDAR data search.
max_return	numeric, indicating the maximum of returns.
preview	logical. If TRUE (default is FALSE), enable or disable previewing LiDAR graphics.
folder	string (optional), indicating an optional folder path where downloaded LiDAR data files will be saved.

Value

dataframe

Note

The lidar_search function simplifies the process of searching for and working with LiDAR data via the TNMAccess API: https://tnmaccess.nationalmap.gov/api/v1/docs.

Examples

```
bbox <- c(-83.742282,42.273389,-83.733442,42.278724)
search_result <- dsmSearch::lidar_search(bbox = bbox,
                                         max_return = 25,
                                         preview = FALSE)
```

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